

Aerodynamic Development of the 2019 Durham University Solar Car

Prof. David Sims-Williams

Outline

Solar Car Aerodynamics Fundamentals

Vehicle Conceptual Design

Aerodynamic Development of DUSC 2019

Build

Test & Compete

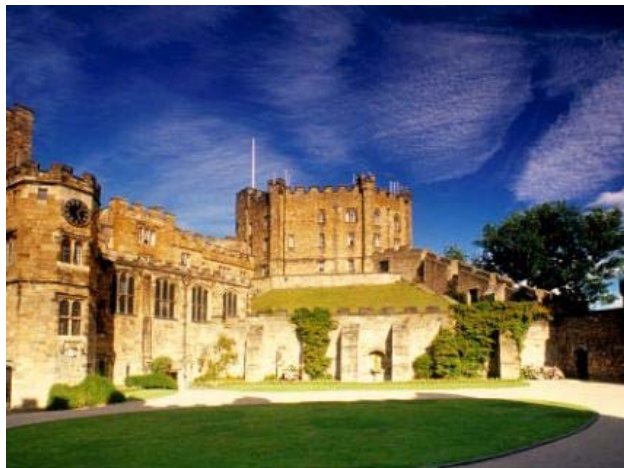


Photo Credit TM Foo

Where is *Durham*?



- Durham is a small city in the North East of England
- 3rd university in England
- First to teach Engineering – in 1838.
- Multi-Disciplinary Engineering programme
 - Good fit for Solar Car



Durham



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Photo Credit TM Foo

Solar Car Aerodynamics - Fundamentals

- Requiring input power from a solar array on the vehicle means:
 - The size of the vehicle will be on the scale of a conventional road car.
 - Must design a car that needs much less power than a conventional road car.
- Main outgoing:
 - Aerodynamics
 - Rolling Resistance

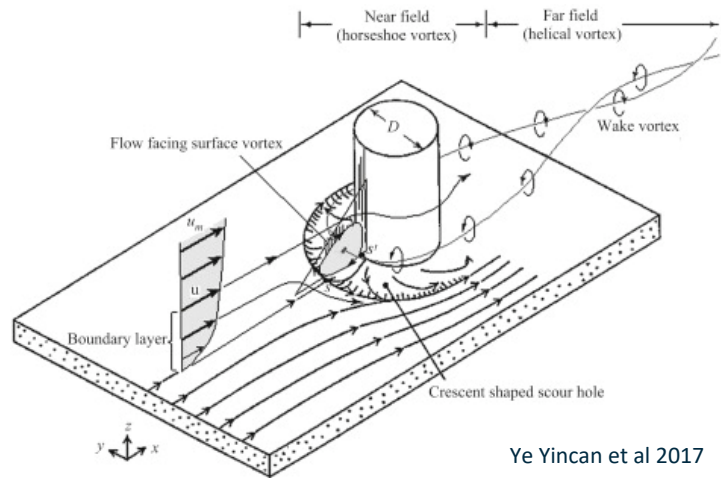


Solar Car Aerodynamics - Fundamentals

- Aerodynamic drag increases with velocity squared.
 - $Drag = C_D A \frac{1}{2} \rho u^2$
 - Aerodynamic power increases with velocity cubed
(Power = Force x Velocity)
- Rolling Resistance is approximately independent of speed.
 - Rolling power will be proportional to velocity
(Power = Force x Velocity)
- For the fastest solar cars – aerodynamics becomes the dominant outgoing.

Solar Car Aerodynamics - Fundamentals

- The first priority is to avoid separated (reversed) flow.
- Then:
 - Avoid lift-induced drag (trailing vortices)
 - Minimise skin-friction (eg: by delaying transition from laminar to turbulent)
- For a low drag vehicle - small things become significant
 - Junction drag – horseshoe vortices
 - Ventilation drag (cooling drag – see [1])
 - Body gaps and steps – see [2], [3]
- Useful references: [4] – Solar Car Aero
[2] – Drag of anything from canopies to bolt heads



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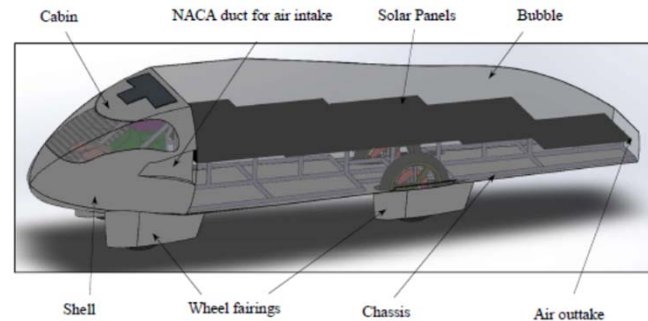
Test & Compete



Photo Credit TM Foo

Vehicle Conceptual Design

- There is a strong interaction between the aerodynamic design and other systems on the car!
 - Previous undergraduate design projects had investigated:
 - vehicle concepts (eg: tilting arrays)
 - suspension space requirements etc.
 - Vehicle configuration was decided by the senior members of the extra-curricular team
 - before any specific aerodynamic development
 - Main aerodynamic development undertaken as a capstone project [5].



Vehicle Conceptual Design

- Separate (/Tilting?) Solar Array Designs

North West University
(South Africa) “Naledi”



Halmstad
“Heart Three”



Chalmers
“Alfrödull”

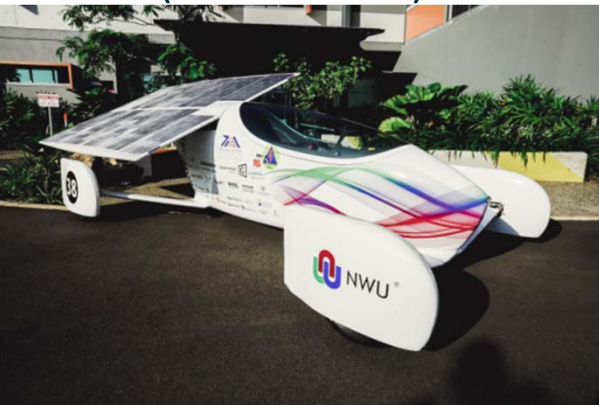


Vehicle Conceptual Design

- Separate (/Tilting?) Solar Array Designs

TILTING ARRAY BRINGS
MORE SOLAR POWER
AERO PENALTY
FROM LARGE SURFACE AREA

North West University
(South Africa) “Naledi”



Halmstad
“Heart Three”



Chalmers
“Alfrödull”



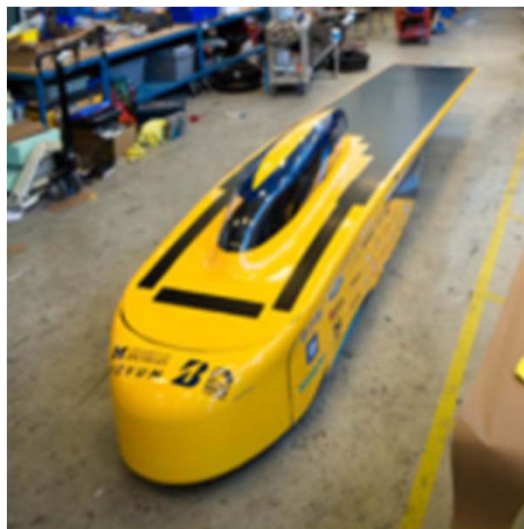
Vehicle Conceptual Design

- “Monohull” Designs

Stanford University
“Black Mamba”



University of Michigan
“Novum”



Cambridge University
“Mirage”



Vehicle Conceptual Design

- “Monohull” Designs

COMPETITIVE AERO
STABILITY?

Stanford University
“Black Mamba”



University of Michigan
“Novum”



Cambridge University
“Mirage”



Vehicle Conceptual Design

- Asymmetric “Catamaran” Designs

TU Delft “Nuna”



University of Western Sydney
“Unlimited 2.0”



Stanford “Sundae”



Vehicle Conceptual Design

- Asymmetric “Catamaran” Designs

LOW FRONTAL AREA
SELECTED

TU Delft “Nuna”



University of Western Sydney
“Unlimited 2.0”



Stanford “Sundae”



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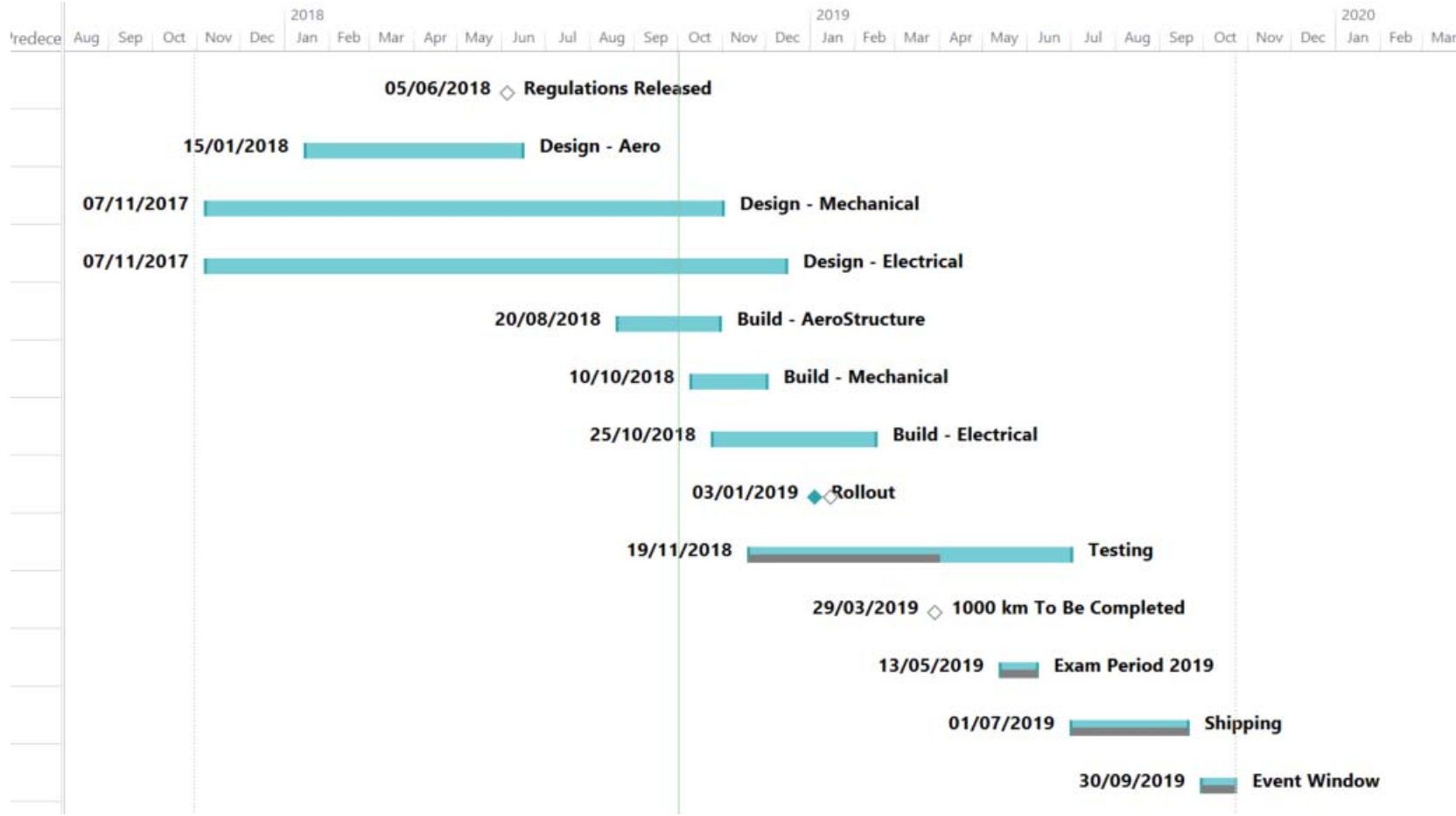
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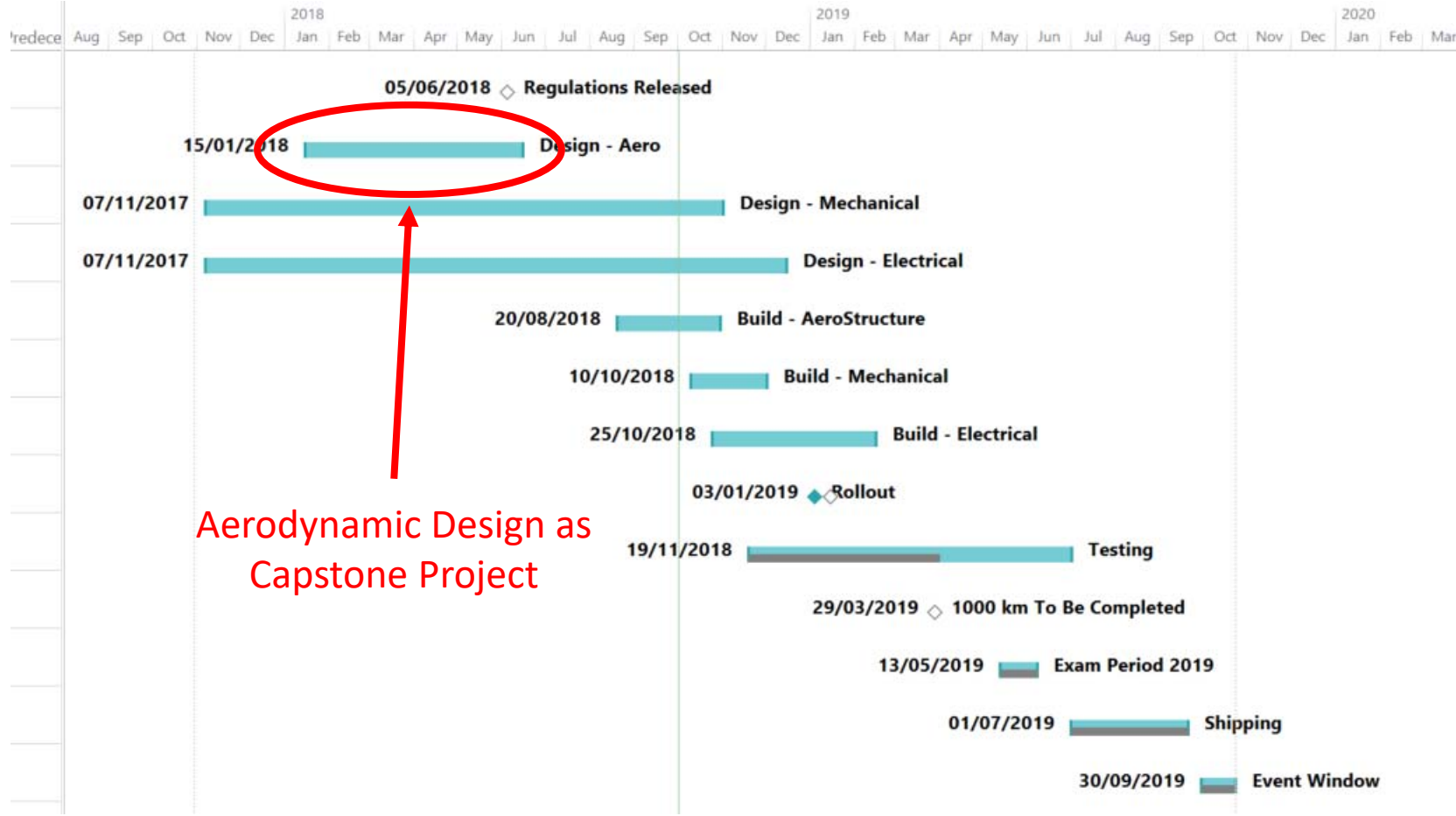


Photo Credit TM Foo

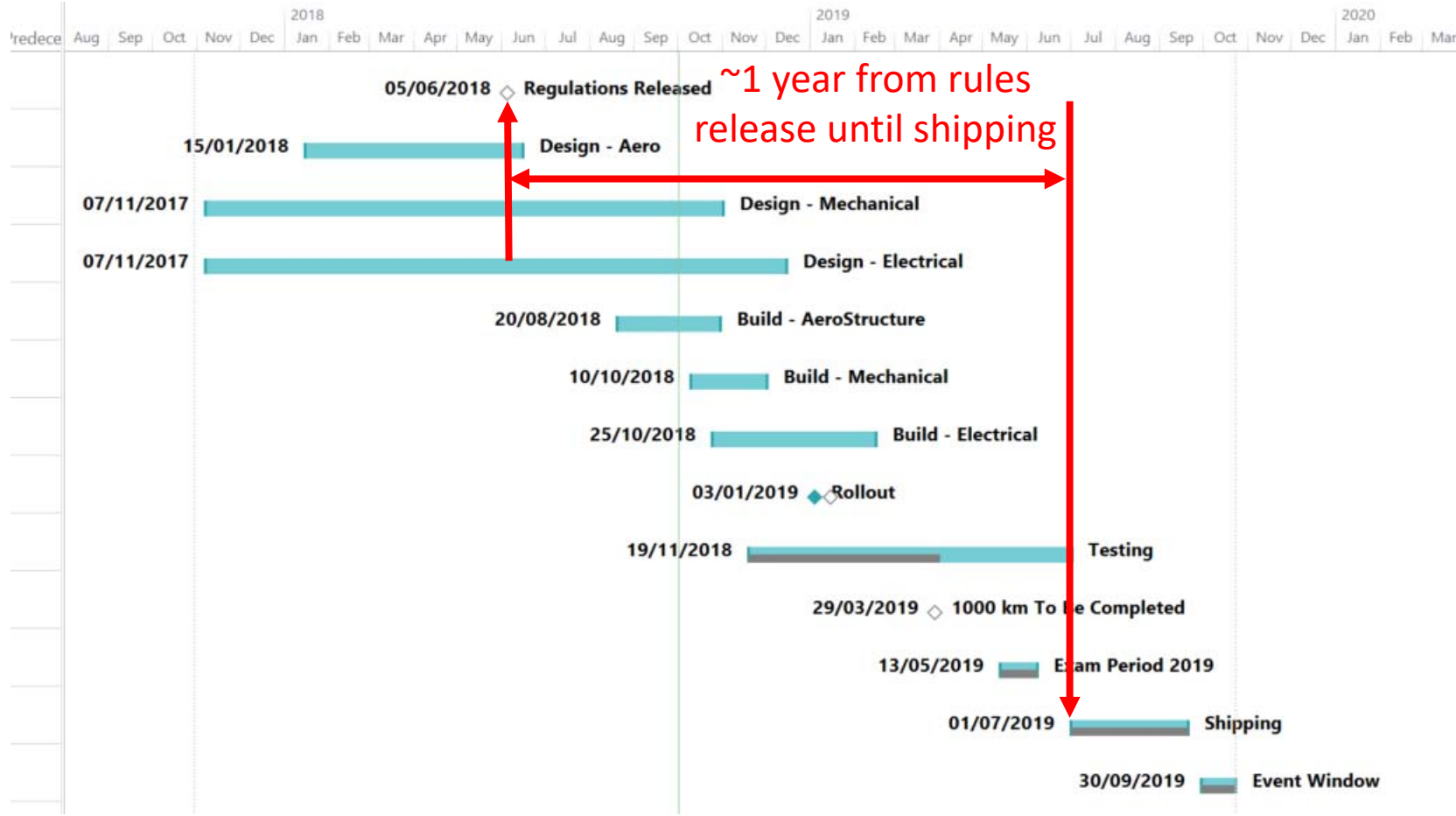
Aerodynamic Development of DUSC 2019



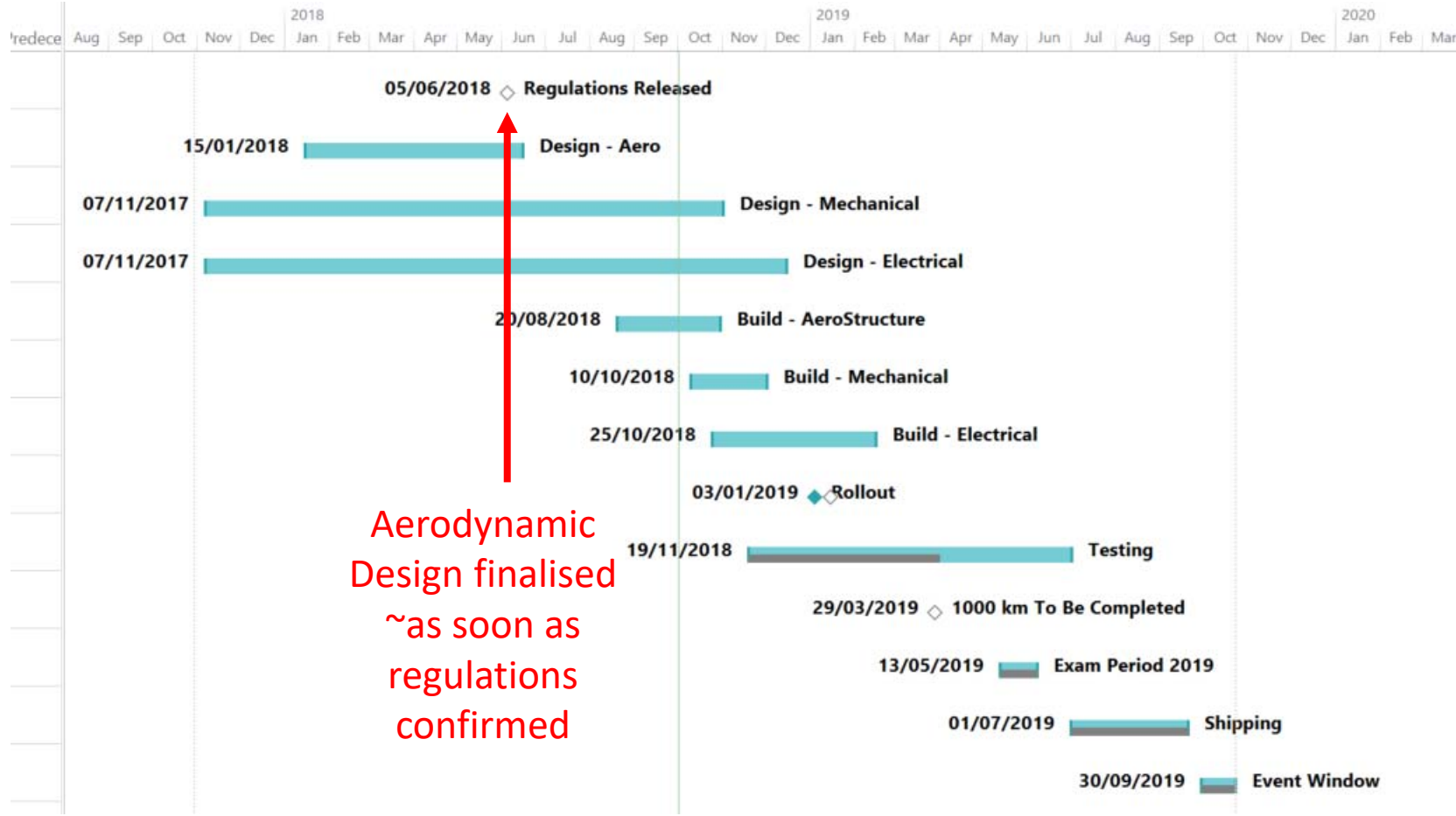
Aerodynamic Development of DUSC 2019



Aerodynamic Development of DUSC 2019

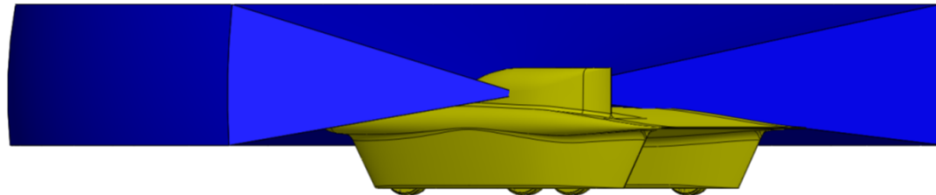
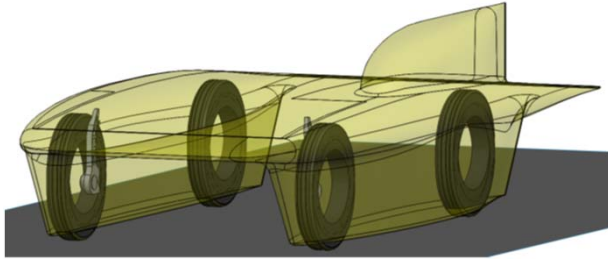


Aerodynamic Development of DUSC 2019



Aerodynamic Development of DUSC 2019

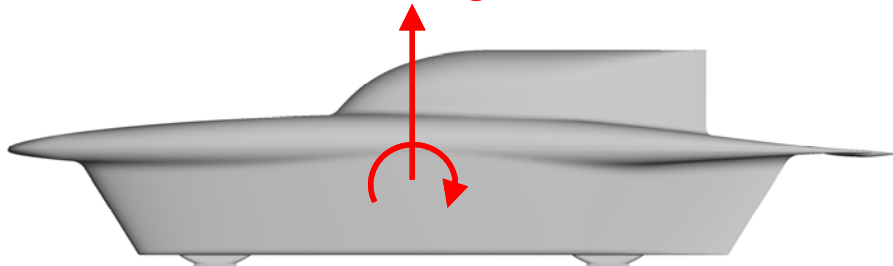
- Starting point:
 - Cell arithmetic, wheels/tyres, driver scan, driver headspace & rollhoop regulations, vision regulations and candidate suspension designs
 - Aerodynamic specification requirements on aerodynamic lift and sideforce resolved at front and rear axles (including yaw – up to 20° - 30°)
 - Aerodynamic drag target(s) (including yaw $\sim 4^\circ$ - 5° is typical)



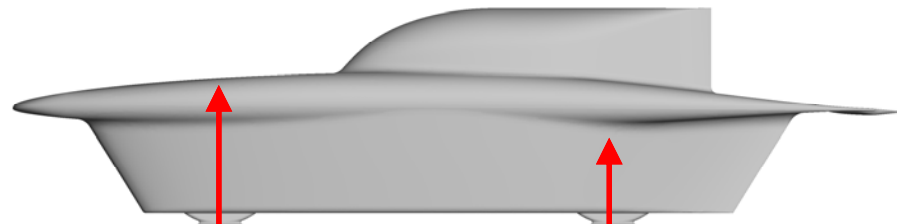
Aerodynamic Development of DUSC 2019

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Lift and Pitching Moment

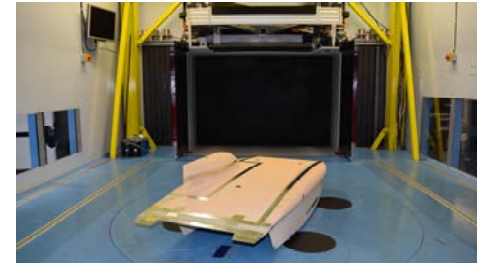
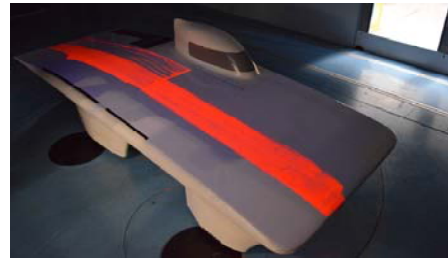
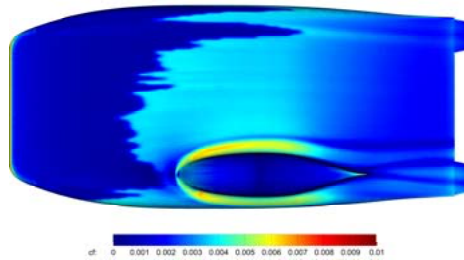
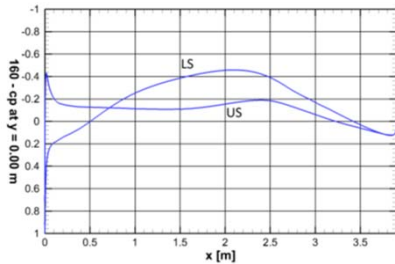


Equivalent Front Lift and Rear Lift



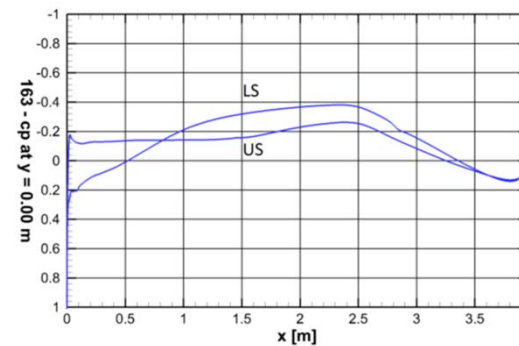
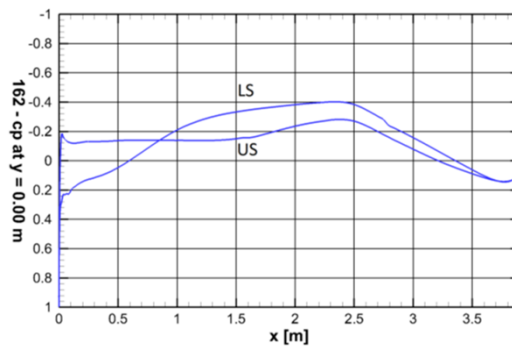
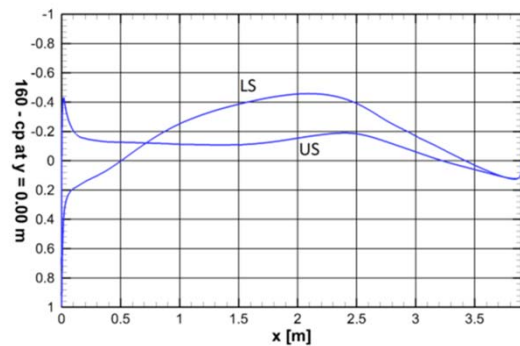
Aerodynamic Development of DUSC 2019

- Overall Process / Toolchain
 - Java Foil – Initial 2D design of main body.
 - Solidworks - Pointwise – Fluent – Tecplot
 - Scale Model Mule Test (Modified DUSC 2015/2017)
 - Scale Model Test of DUSC 2019



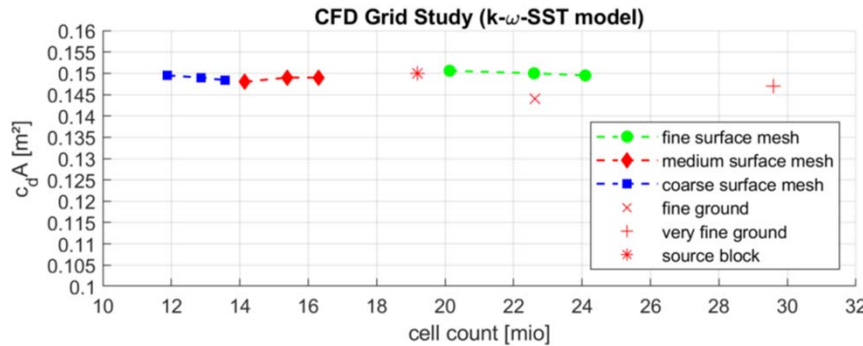
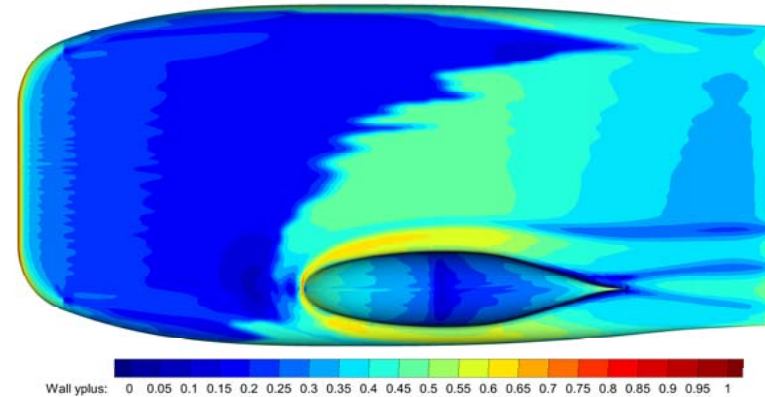
Aerodynamic Development of DUSC 2019

- Java Foil – Initial 2D design of main body.
 - Starting point: NACA 66009 laminar flow profile (see [6] for aerofoils)
 - Java Foil inverse design used to match baseline pressure distribution when in ground effect.



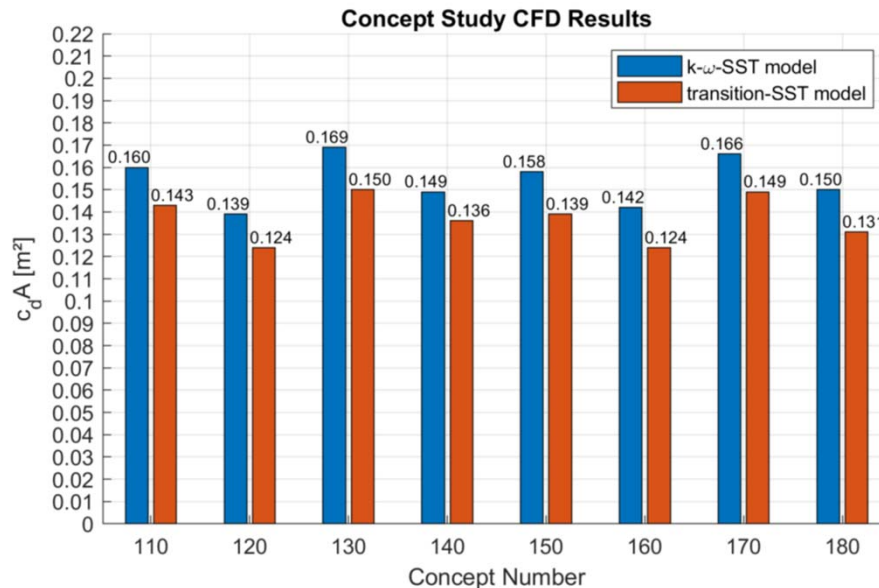
Aerodynamic Development of DUSC 2019

- Solidworks - Pointwise – Fluent – Tecplot – Main Design Development
 - Automated re-meshing when CAD geometry modified
 - Meshing in Pointwise
 - Quad-dominated surface mesh
 - Prism boundary layer mesh $y^+ < 1$
 - Tetrahedral mesh in far field
 - 24-30M cells.



Aerodynamic Development of DUSC 2019

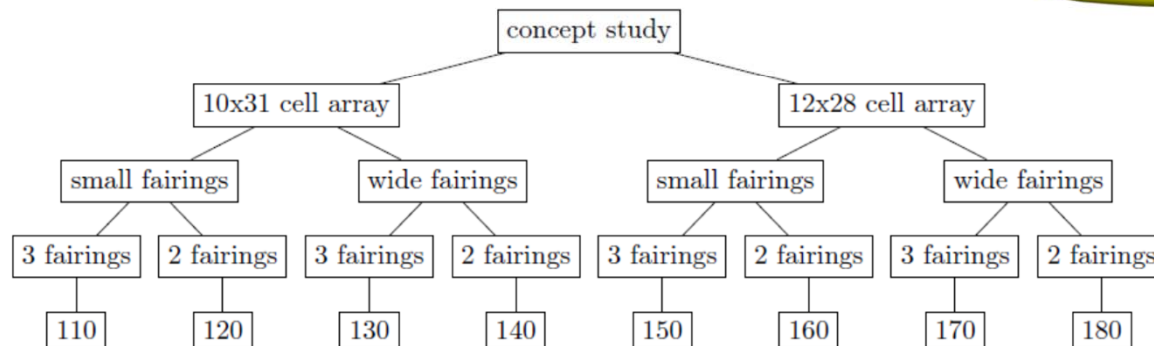
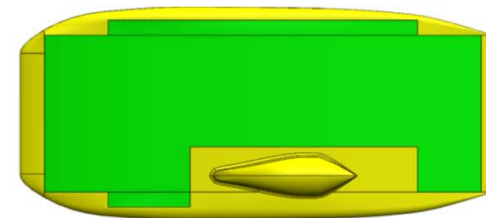
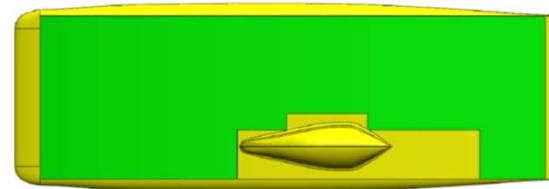
- Solidworks - Pointwise – Fluent – Tecplot – Main Design Development
 - Simulations ran overnight on 4 core Intel Xeon 3.7 GHz m/cs with 64Gb RAM
 - $k-\omega$ -SST and transition-SST models used.



Figures from [5]

Aerodynamic Development of DUSC 2019

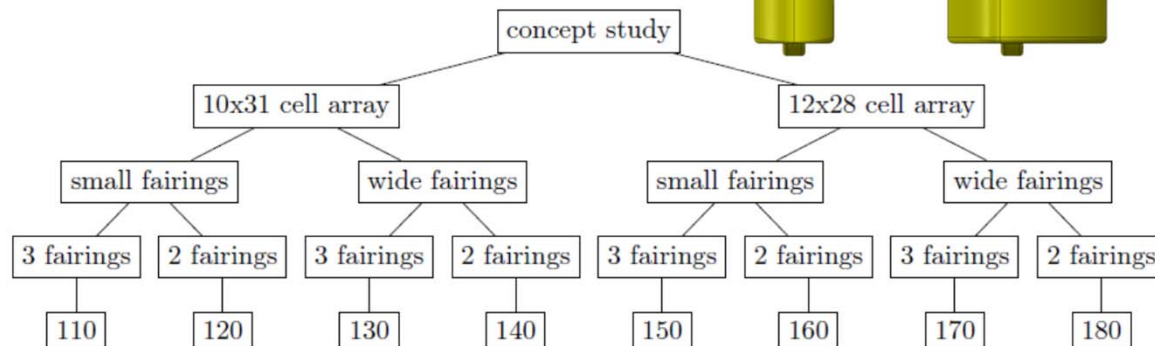
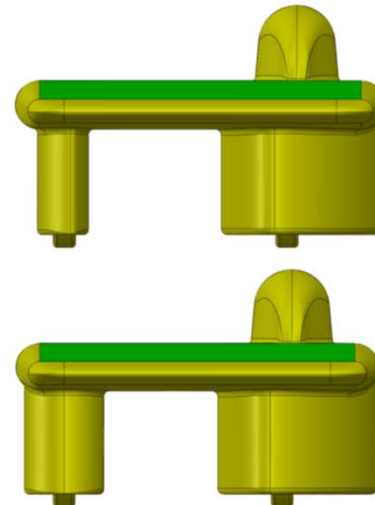
- Solidworks - Pointwise – Fluent – Tecplot – Main Design Development
 - 10x31 cell array vs 12x28 cell array
 - Small Fairings vs Wide Fairings
 - 3 Fairings vs 2 Fairings



Figures from [5]

Aerodynamic Development of DUSC 2019

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Figures from [5]

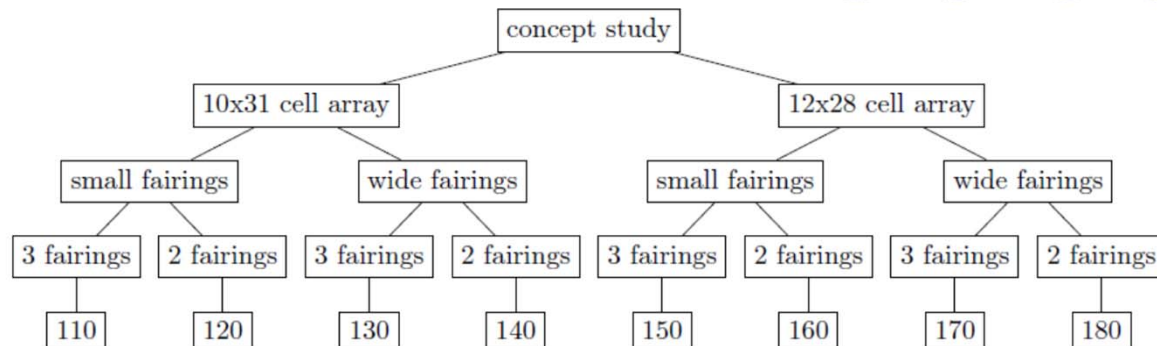
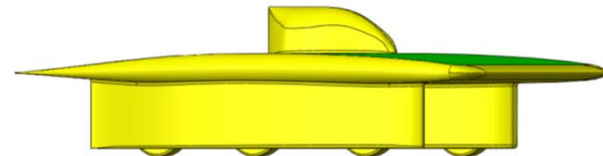
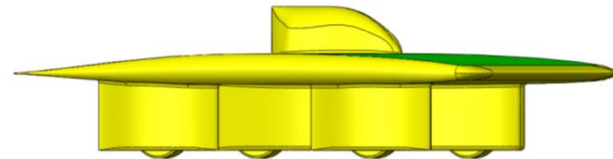
Aerodynamic Development of DUSC 2019

- Small fairings reduce vehicle aero drag
..... but are too narrow to allow the vehicle to steer
- Hence small fairings with opening doors when driver steers
- Need to be well-Engineered to work in practice!



Aerodynamic Development of DUSC 2019

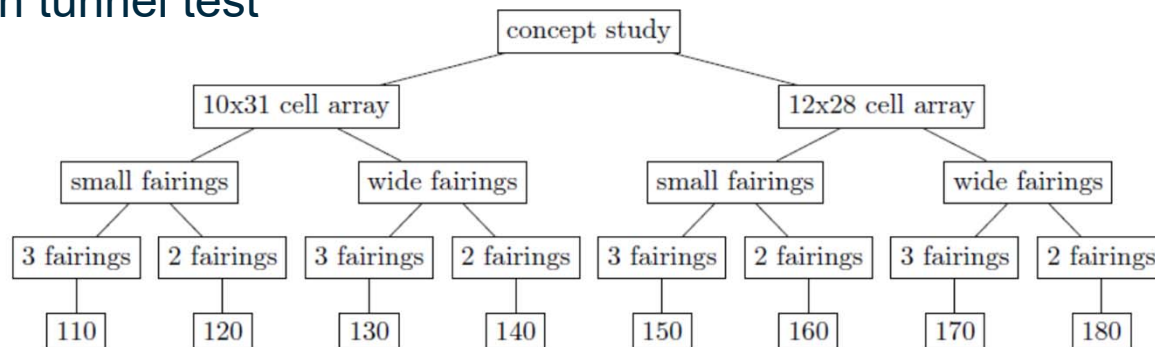
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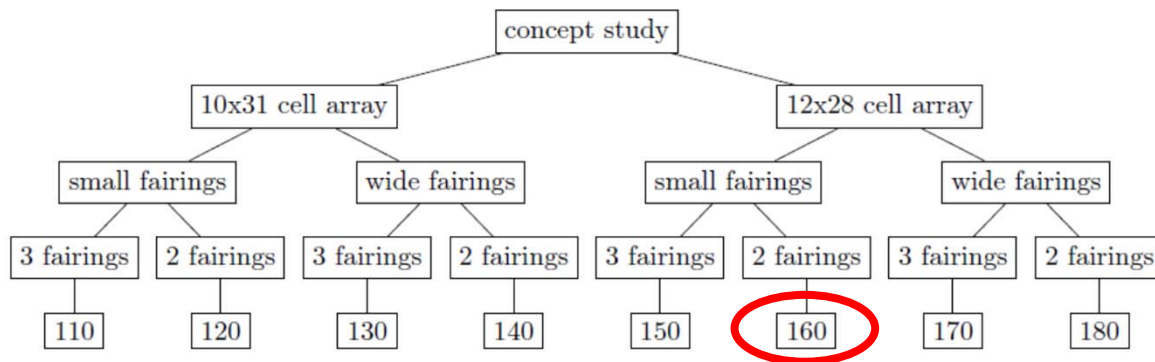
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 - Conflicting CFD results
 - Ran tunnel test



Figures from [5]
Model by [7]

Aerodynamic Development of DUSC 2019

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Aerodynamic Development of DUSC 2019

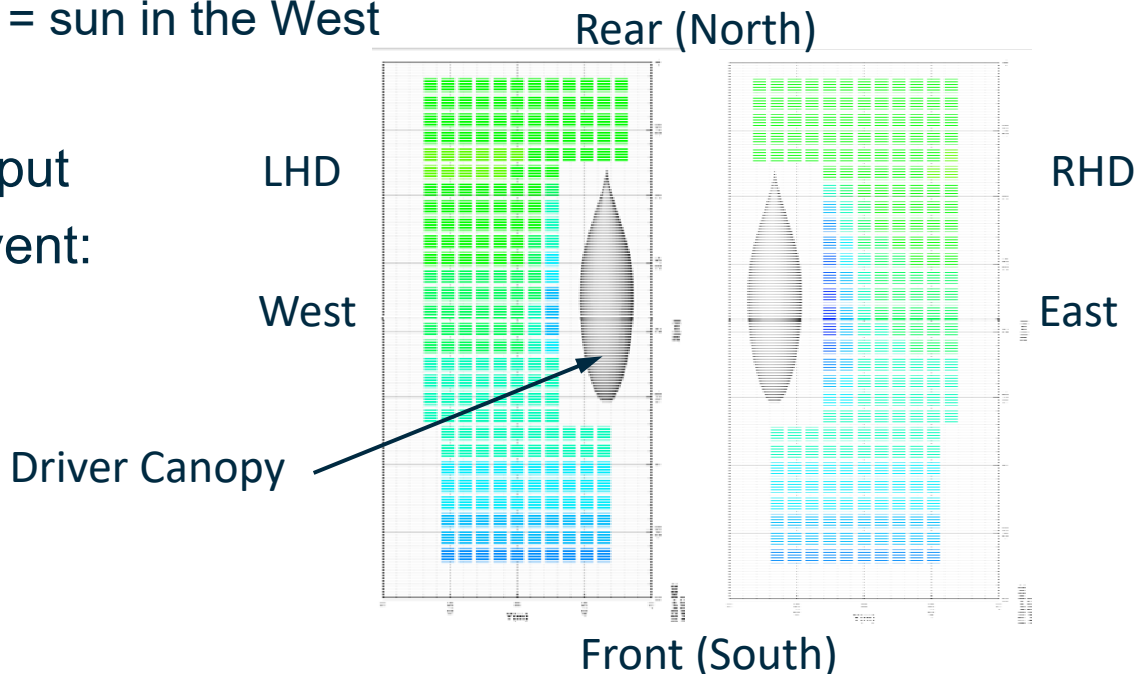
- Left Hand Drive? (The United Kingdom and Australia are both Right Hand Drive countries)
 - Drive: North to South, 8am-5pm
 - 4 hours before noon = sun in the East
 - 5 hours after noon = sun in the West



Aerodynamic Development of DUSC 2019

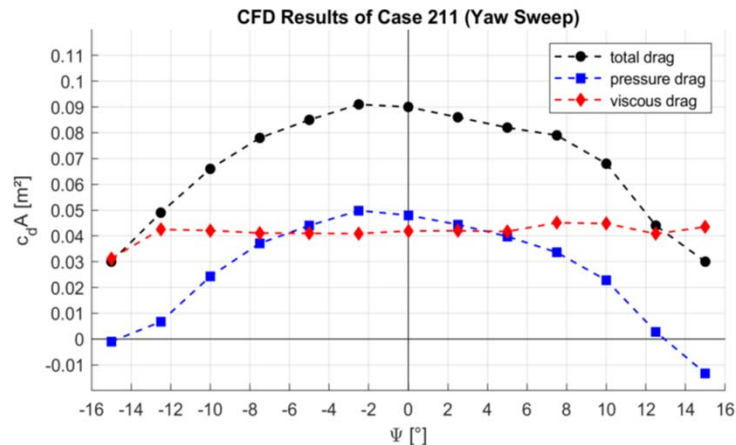
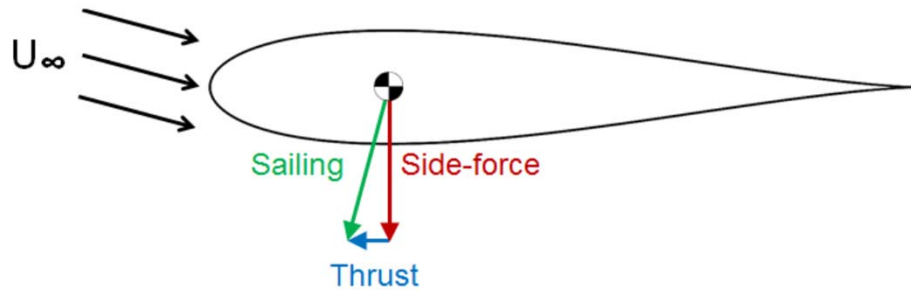
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Simulated solar output
cell by cell over event:



Aerodynamic Development of DUSC 2019

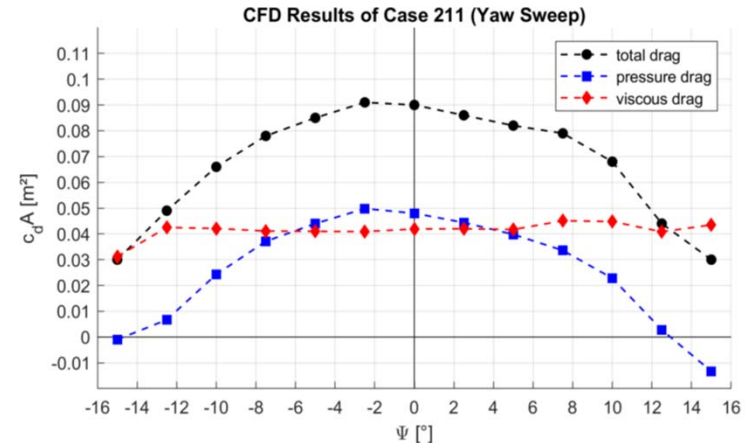
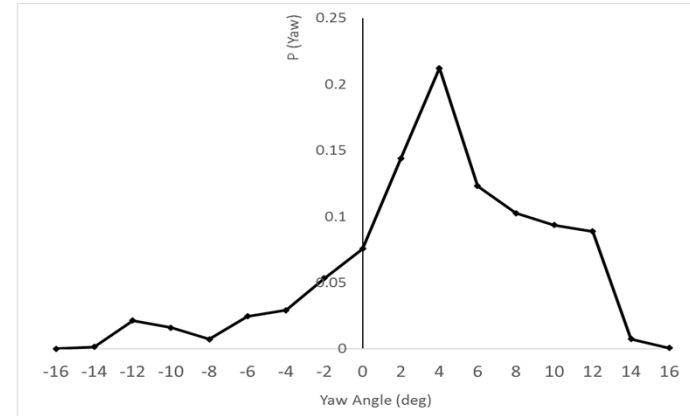
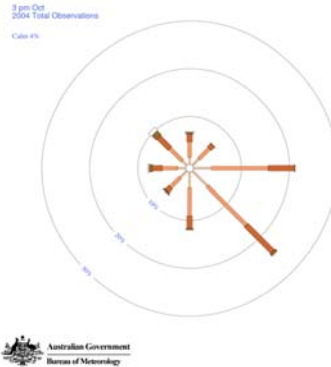
- Left Hand Drive?
 - Crosswinds on wheel fairings provide sailing thrust
 - Reduces drag at yaw



Aerodynamic Development of DUSC 2019

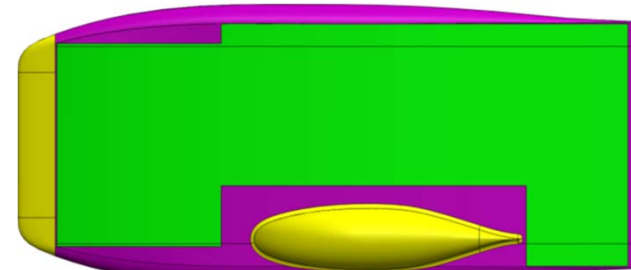
- Left Hand Drive?
 - Drive: North to South, 8am-5pm
 - Prevailing wind is from the East

Alice Springs
3pm in October
1942-2016

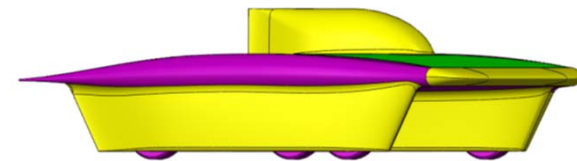
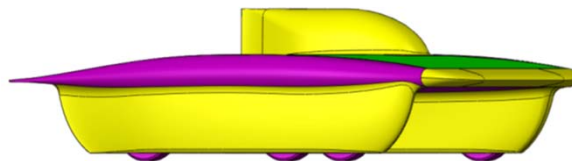
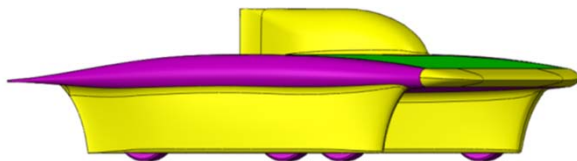


Aerodynamic Development of DUSC 2019

- Solidworks - Pointwise – Fluent – Tecplot – Main Design Development
 - Progressive refinement:
 - Cell arrangement
 - Leading edge
 - Canopy
 - Wheel Fairing Leading and Trailing Edges



Case 207



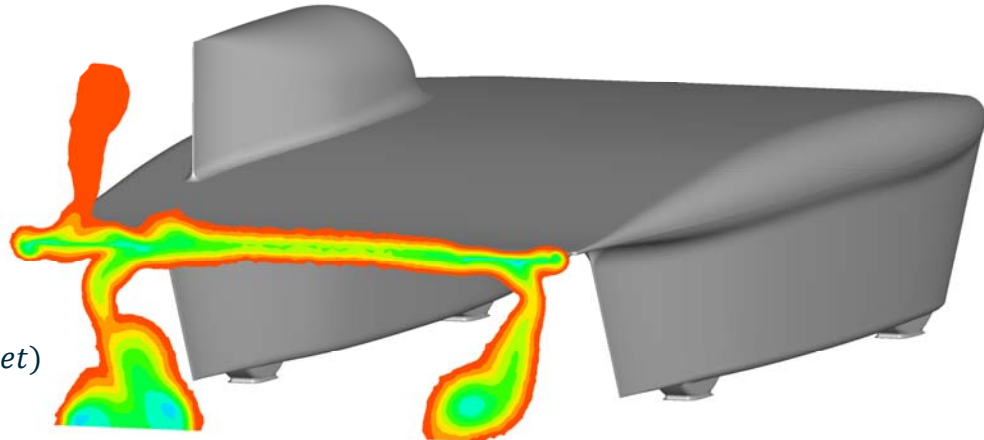
Aerodynamic Development of DUSC 2019

- Solidworks - Pointwise – Fluent – Tecplot – Main Design Development
 - Progressive refinement:
 - Forces (C_{DA} , C_{LAF} , C_{LAR}) are the bottom line.
 - Flowfield provides guidance on how to improve.
 - Automated standard plots for every case.
 - Wake Total Pressure

Contours of total
pressure coefficient

$$C_{PTot} = \frac{\left(P + \frac{1}{2}\rho u^2\right) - P_{\infty}}{\frac{1}{2}\rho u_{\infty}^2}$$

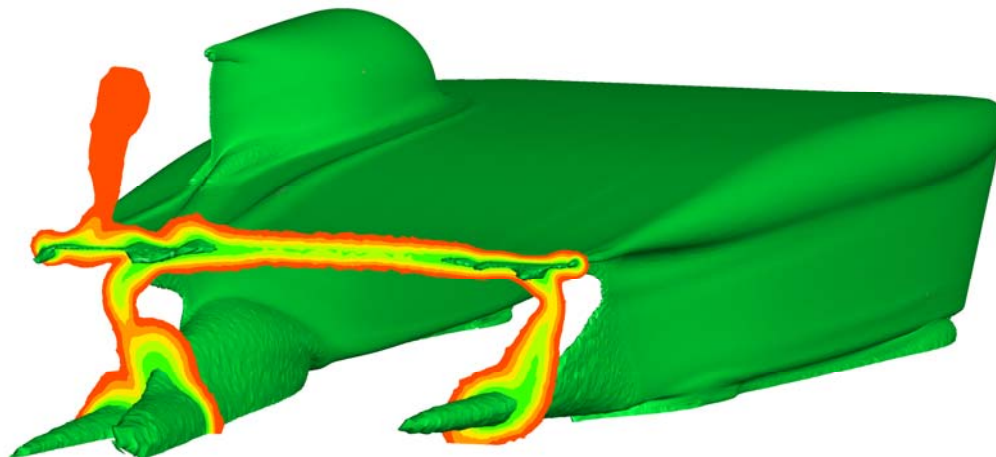
where ∞ denotes freestream (inlet)



Aerodynamic Development of DUSC 2019

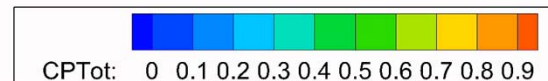
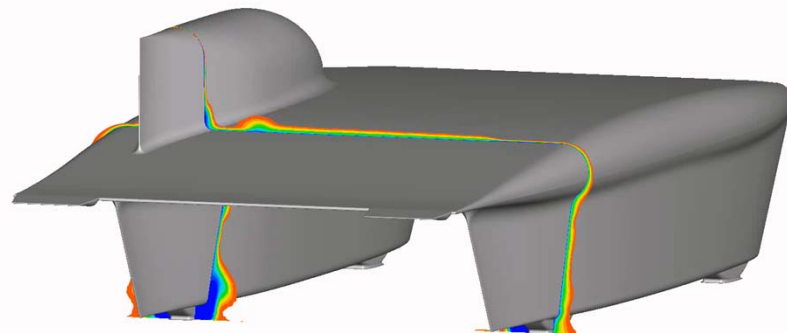
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 - Wake Total Pressure

Contours of total
pressure coefficient
+
Isosurface at
 $C_{PTot}=0.5$



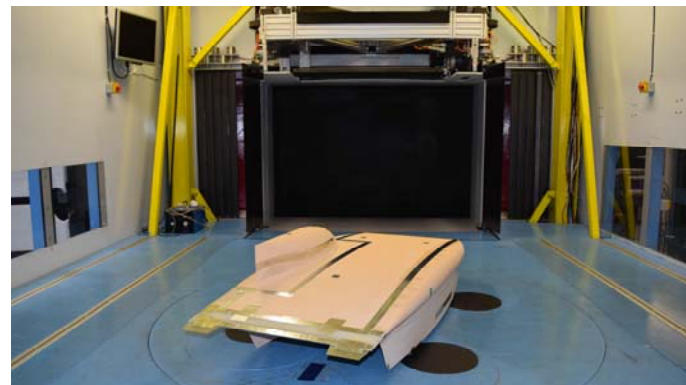
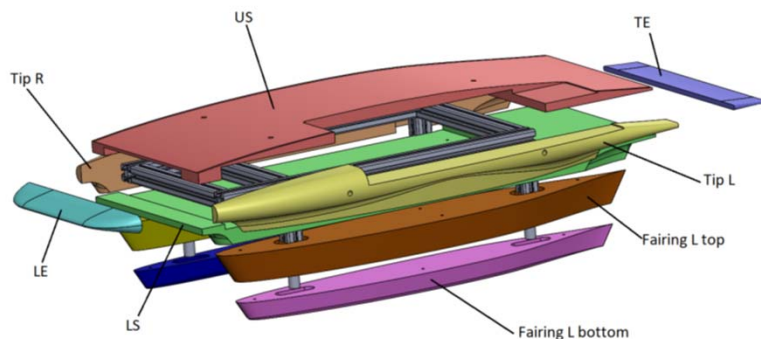
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Aerodynamic Development of DUSC 2019

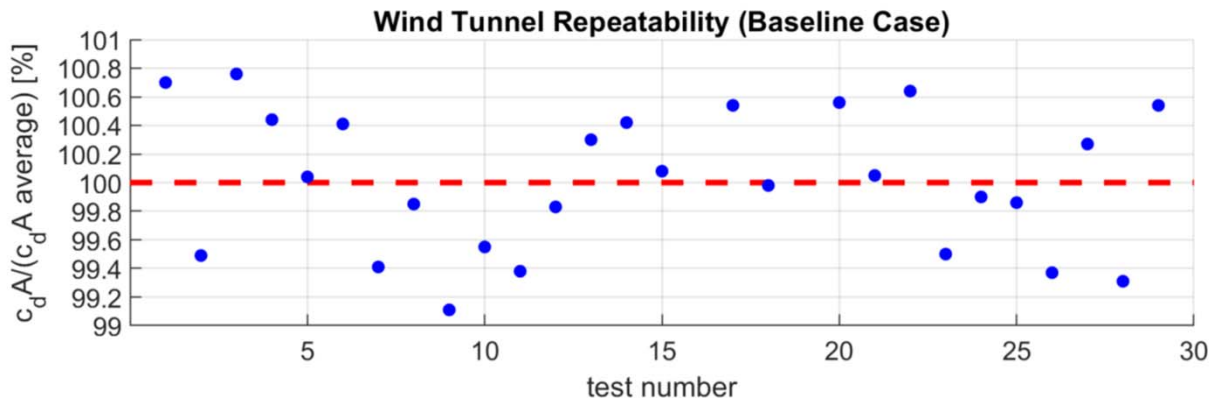
- Scale Model Test of DUSC 2019
 - 35% Scale Model
 - Necuron 480 Model Board on Aluminium Frame
 - Detail parts rapid prototyped on Objet Eden 500V
 - Durham 2m² Wind Tunnel in Fixed Ground Configuration
 - Blockage < 5%
 - $Re = 2.3 \times 10^6$ (30 m/s)



Figures from [5]

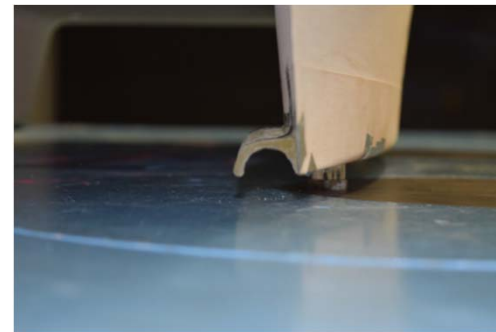
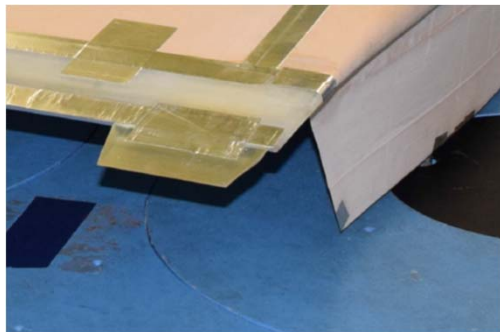
Aerodynamic Development of DUSC 2019

- Scale Model Test of DUSC 2019
 - Wind tunnel results >10% higher on $C_D A$ vs CFD at same Re.
 - ~30 repeats of baseline config. over the test programme all within 1% ($0.001\text{m}^2 C_D A$ Full Scale)



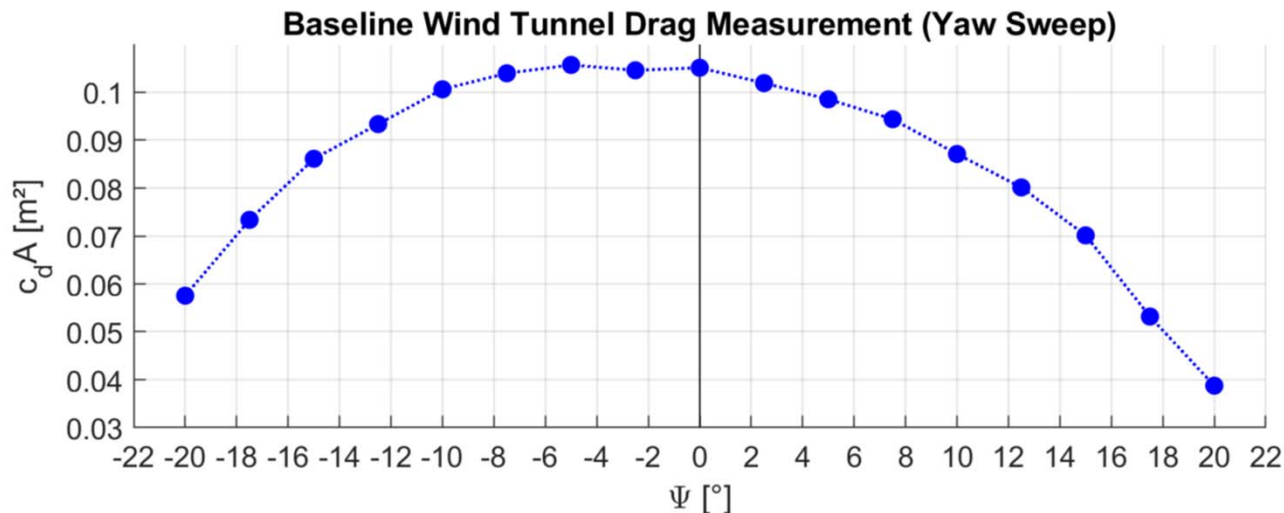
Aerodynamic Development of DUSC 2019

- Scale Model Test of DUSC 2019
 - Refinement of rear lights
 - Investigation of impacts of small devices (winglets, footplates etc).
 - Detailed Yaw Sweep
 - Effects of Pitch and Rideheight



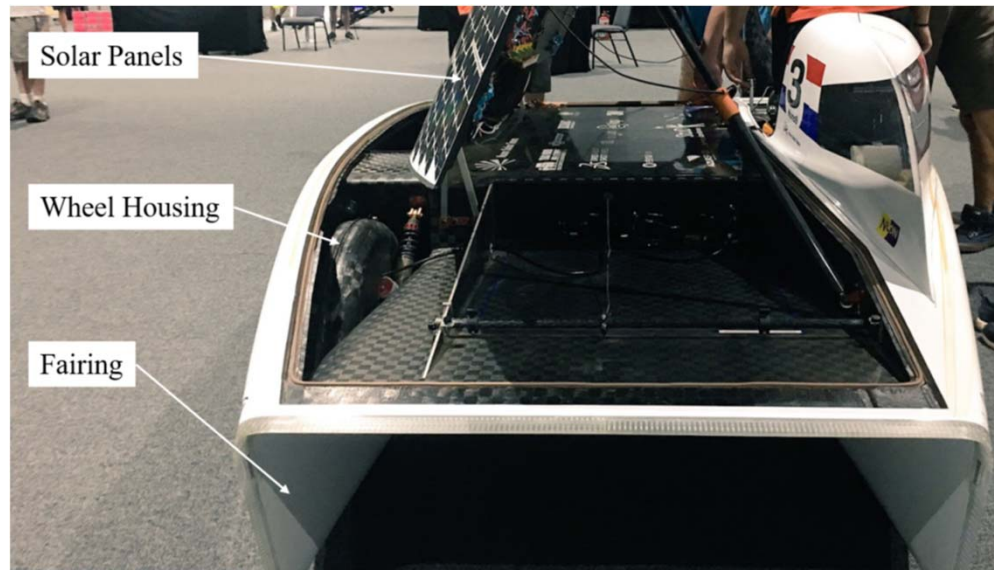
Aerodynamic Development of DUSC 2019

- Zero Yaw:
 - $C_{DA} = 0.105\text{m}^2$ (wind tunnel, model Re), 0.092m^2 (CFD, full scale Re)
 - and yaw makes things better...



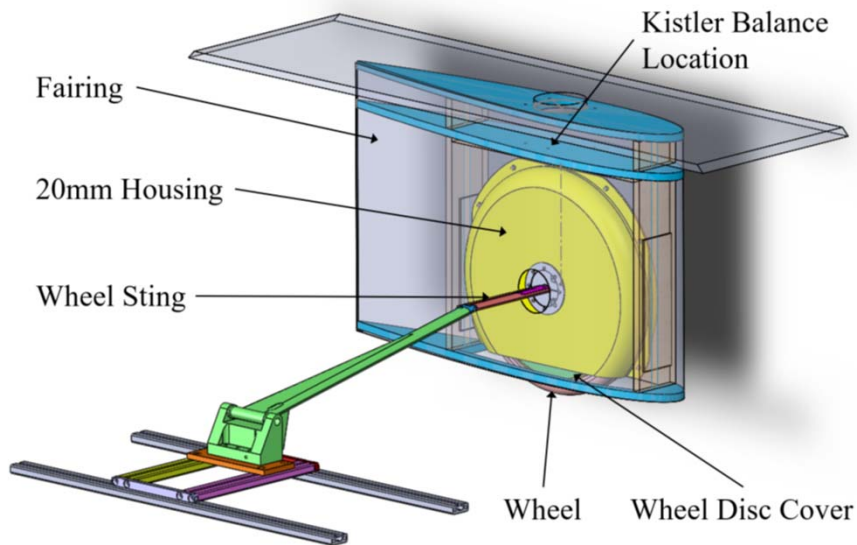
Aerodynamic Development of DUSC 2019

- Wheel Inner Housings
 - Used by several teams
(but not on Durham cars...)
 - Tight fitting wheel housings within the wheel fairing
 - Move with the suspension and steering



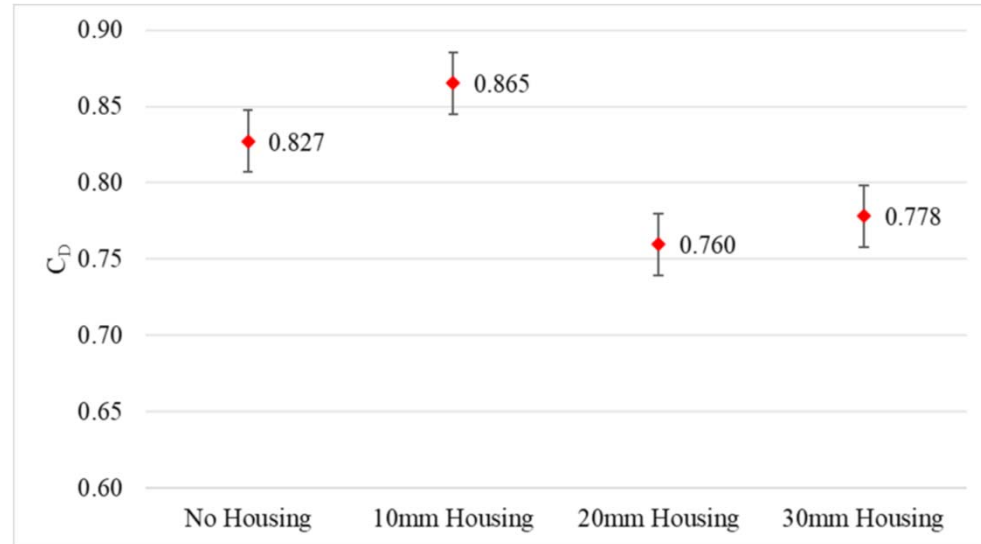
Aerodynamic Development of DUSC 2019

- Wheel Inner Housings
 - CFD & Wind Tunnel investigation at full scale as capstone project



Aerodynamic Development of DUSC 2019

- Wheel Inner Housings
 - CFD & Wind Tunnel investigation at full scale as capstone project
 - Wheel housings can provide a drag saving
 - The gain is $\Delta C_D = -0.067$ based on wheel frontal area which is $\sim \Delta C_D A = -0.01 \text{m}^2$ on the vehicle.
 - A tight fit is good, but too tight a fit can increase drag relative to not having an inner housing.



Outline

Solar Car Aerodynamics Fundamentals

Vehicle Conceptual Design

Aerodynamic Development of DUSC 2019

Build

Test & Compete



Photo Credit TM Foo

Build

- Positive patterns machined in modelboard
 - ~1000 hours machining time
- Pattern pieces assembled & painted
- Sanded and Polished
- Wet-Layup of Fibreglass-Epoxy Moulds
- Cure in Vacuum Bag
- 8 Piece Main Mould
- Monocoque Chassis
 - Carbon (+Kevlar) Skin, Rohacell Core
 - Pre-preg with vacuum cure in oven
 - Chassis ~40 kg, whole car: 175 kg



Build

- Positive patterns machined in modelboard
 - ~1000 hours machining time
- Pattern pieces assembled & painted
- Sanded and Polished
- Wet-Layup of Fibreglass-Epoxy Moulds
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 - Chassis ~40 kg, whole car: 175 kg



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 - ~1000 hours machining time
- **Pattern pieces assembled & painted**
- Sanded and Polished
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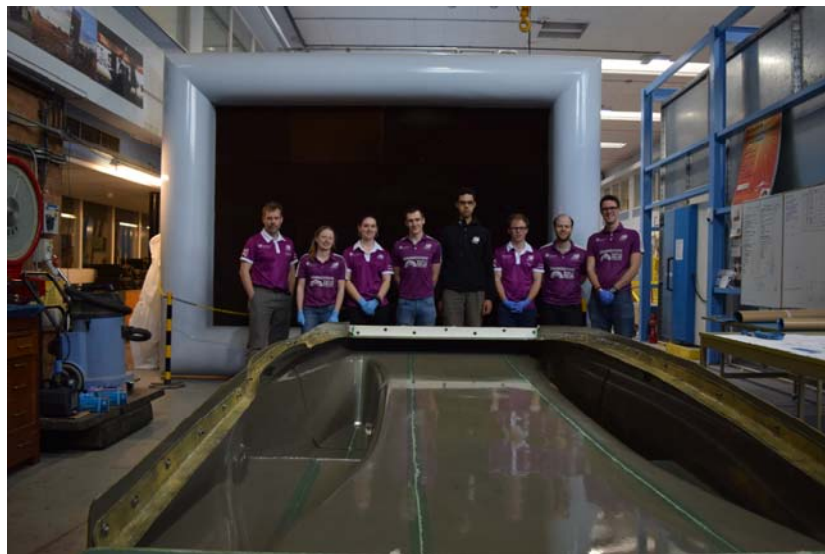
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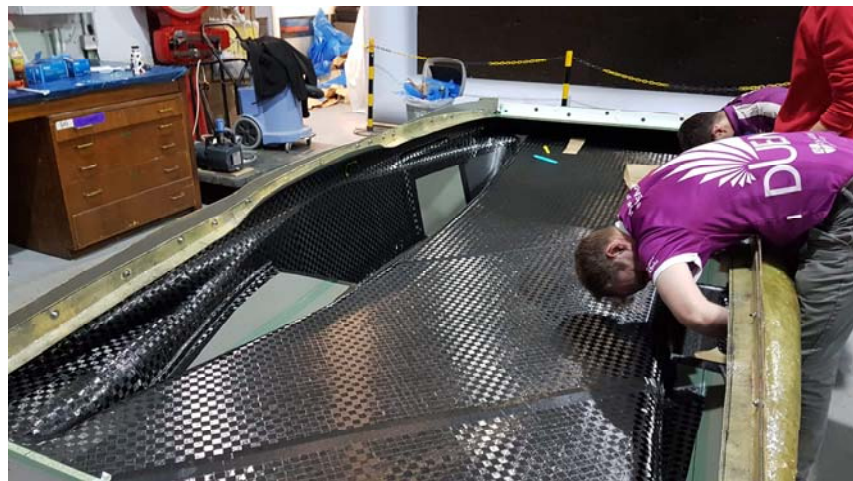
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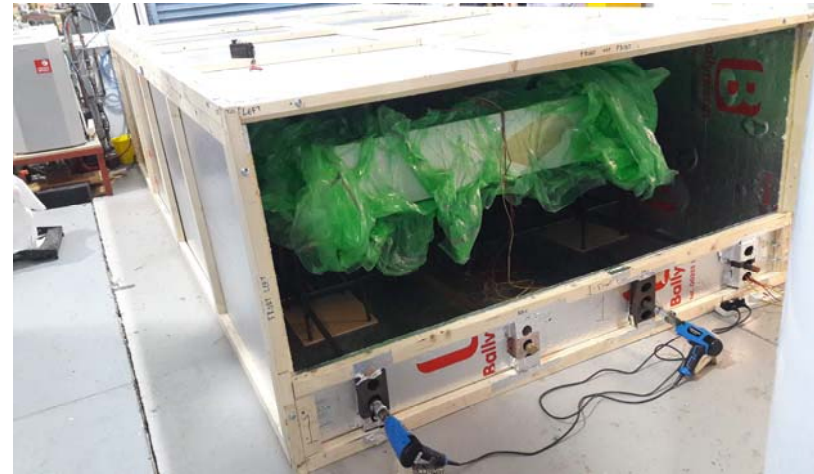
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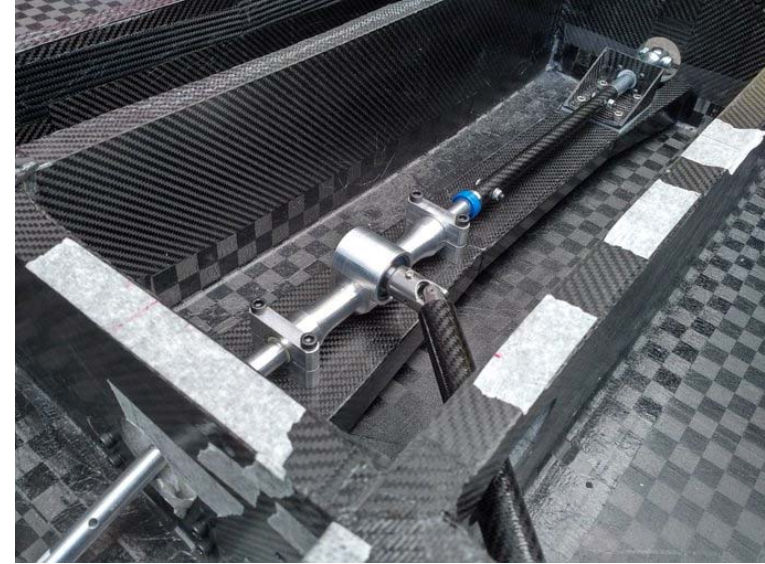
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Outline

Solar Car Aerodynamics Fundamentals

Vehicle Conceptual Design

Aerodynamic Development of DUSC 2019

Build

Test & Compete



Photo Credit TM Foo

Test and Compete

- Testing at Bruntingthorpe Proving Ground
- Ship / Fly to Australia
- Hot-Weather Testing
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 - Drove North Coast to South Coast, just short of Adelaide...
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References

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More Information



- <http://www.duem.org>
- <https://www.dur.ac.uk/engineering/>



- https://twitter.com/DUEM_Electric



- DUEM_electric @DUEM_electric



- https://www.youtube.com/channel/UCCEutnq5g_Lq2fbb7VHG5bQ

Aerodynamic Development of the 2019 Durham University Solar Car

Prof. David Sims-Williams